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Permanent Link to Straight Talk on Anti-Spoofing: Securing the Future of PNT
2021/03/25

By Kyle Wesson, Daniel Shepard, and Todd Humphreys

Disruption created by intentional generation of fake GPS signals could have serious economic consequences. This article discusses how typical civil GPS receivers respond to an advanced civil GPS spoofing attack, and four techniques to counter such attacks: spread-spectrum security codes, navigation message authentication, dual-receiver correlation of military signals, and vestigial signal defense. Unfortunately, any kind of anti-spoofing, however necessary, is a tough sell. GPS spoofing has become a hot topic. At the 2011 Institute of Navigation (ION) GNSS conference, 18 papers discussed spoofing, compared with the same number over the past decade. ION-GNSS also featured its first panel session on anti-spoofing, called “Improving Security of GNSS Receivers,” which offered six security experts a forum to debate the most promising anti-spoofing technologies. The spoofing threat has also drawn renewed U.S. government scrutiny since the initial findings of the 2001 Volpe Report. In November 2010, the U.S. Position Navigation and Timing National Executive Committee requested that the U.S. Department of Homeland Security (DHS) conduct a comprehensive risk assessment on the use of civil GPS. In February 2011, the DHS Homeland Infrastructure Threat and Risk Analysis Center began its investigation in conjunction with subject-matter experts in academia, finance, power, and telecommunications, among others. Their findings will be summarized in two forthcoming reports, one on the spoofing and jamming threat and the other on possible mitigation techniques. The reports are anticipated to show that GPS disruption due to spoofing or jamming could have serious economic consequences. Effective techniques exist to defend receivers against spoofing attacks. This article summarizes state-of-the-art anti-spoofing techniques and suggests a path forward to equip civil GPS receivers with these defenses. We start with an analysis of a typical civil GPS receiver’s response to our laboratory’s powerful spoofing device. This will illustrate the range of freedom a spoofer has when commandeering a victim receiver’s tracking loops. We will then provide an overview of promising cryptographic and non-cryptographic anti-spoofing techniques and highlight the obstacles that impede their widespread adoption. The Spoofing Threat Spoofing is

the transmission of matched-GPS-signal-structure interference in an attempt to commandeer the tracking loops of a victim receiver and thereby manipulate the receiver's timing or navigation solution. A spoofer can transmit its counterfeit signals from a stand-off distance of several hundred meters or it can be co-located with its victim. Spoofing attacks can be classified as simple, intermediate, or sophisticated in terms of their effectiveness and subtlety. In 2003, the Vulnerability Assessment Team at Argonne National Laboratory carried off a successful simple attack in which they programmed a GPS signal simulator to broadcast high-powered counterfeit GPS signals toward a victim receiver. Although such a simple attack is easy to mount, the equipment is expensive, and the attack is readily detected because the counterfeit signals are not synchronized to their authentic counterparts. In an intermediate spoofing attack, a spoofer synchronizes its counterfeit signals with the authentic GPS signals so they are code-phase-aligned at the target receiver. This method requires a spoofer to determine the position and velocity of the victim receiver, but it affords the spoofer a serious advantage: the attack is difficult to detect and mitigate. The sophisticated attack involves a network of coordinated intermediate-type spoofers that replicate not only the content and mutual alignment of visible GPS signals but also their spatial distribution, thus fooling even multi-antenna spoofing defenses.

Table 1. Comparison of anti-spoofing techniques discussed in this article. Lab Attack.

So far, no open literature has reported development or research into the sophisticated attack. This is likely because of the success of the intermediate-type attack: to date, no civil GPS receiver tested in our laboratory has fended off an intermediate-type spoofing attack. The spoofing attacks, which are always conducted via coaxial cable or in radio-frequency test enclosures, are performed with our laboratory's receiver-spoofers, an advanced version of the one introduced at the 2008 ION-GNSS conference (see "Assessing the Spoofing Threat," GPS World, January 2009). To commence the attack, the spoofer transmits its counterfeit signals in code-phase alignment with the authentic signals but at power level below the noise floor. The spoofer then increases the power of the spoofed signals so that they are slightly greater than the power of the authentic signals. At this point, the spoofer has taken control of the victim receiver's tracking loops and can slowly lead the spoofed signals away from the authentic signals, carrying the receiver's tracking loops with it. Once the spoofed signals have moved more than 600 meters in position or 2 microseconds in time away from the authentic signals, the receiver can be considered completely owned by the spoofer. Spoofing testbed at the University of Texas Radionavigation Laboratory, an advanced and powerful suite for anti-spoofing research. On the right are several of the civil GPS receivers tested and the radio-frequency test enclosure, and on the left are the phasor measurement unit and the civil GPS spoofer. Although our spoofer fooled all of the receivers tested in our laboratory, there are significant differences between receivers' dynamic responses to spoofing attacks. It is important to understand the types of dynamics that a spoofer can induce in a target receiver to gain insight into the actual dangers that a spoofing attack poses rather than rely on unrealistic assumptions or models of a spoofing attack. For example, a recent paper on time-stamp manipulation of the U.S. power grid assumed that there was no limit to the rate of change that a spoofer could impose on a victim receiver's position and timing solution, which led to unrealistic conclusions. Experiments performed in our laboratory sought to answer three specific questions regarding spoofer-induced

dynamics: How quickly can a timing or position bias be introduced? What kinds of oscillations can a spoofer cause in a receiver's position and timing? How different are receiver responses to spoofing? These questions were answered by determining the maximum spoofer-induced pseudorange acceleration that can be used to reach a certain final velocity when starting from a velocity of zero, without raising any alarms or causing the target receiver to lose satellite lock. The curve in the velocity-acceleration plane created by connecting these points defines the upper bound of a region within which the spoofer can safely manipulate the target receiver. These data points can be obtained empirically and fit to an exponential curve. Alarms on the receiver may cause some deviations from this curve depending on the particular receiver. Figure 1 shows an example of the velocity-acceleration curve for a high-quality handheld receiver, whose position and timing solution can be manipulated quite aggressively during a spoofing attack. These results suggest that the receiver's robustness — its ability to provide navigation and timing solutions despite extreme signal dynamics — is actually a liability in regard to spoofing. The receiver's ability to track high accelerations and velocities allows a spoofer to aggressively manipulate its navigation solution. Figure 1. Theoretical and experimental test results for a high-quality handheld receiver's dynamic response to a spoofing attack. Although not shown here, the maximum attainable velocity is around 1,300 meters/second. The relative ease with which a spoofer can manipulate some GPS receivers suggests that GPS-dependent infrastructure is vulnerable. For example, the telecommunications network and the power grid both rely on GPS time-reference receivers for accurate timing. Our laboratory has performed tests on such receivers to determine the disruptions that a successful spoofing attack could cause. The remainder of this section highlights threats to these two sectors of critical national infrastructure.

Cell-Phone Vulnerability. Code division multiple access (CDMA) cell-phone towers rely on GPS timing for tower-to-tower synchronization. Synchronization prevents towers from interfering with one another and enables call hand-off between towers. If a particular tower's time estimate deviates more than 10 microseconds from GPS time, hand-off to and from that tower is disrupted. Our tests indicate that a spoofer could induce a 10-microsecond time deviation within about 30 minutes for a typical CDMA tower setup. A spoofer, or spoofer network, could also cause multiple neighboring towers to interfere with one another. This is possible because CDMA cell-phone towers all use the same spreading code and distinguish themselves only by the phasing (that is, time offset) of their spreading codes. Furthermore, it appears that a spoofer could impair CDMA-based E911 user-location.

Power-Grid Vulnerability. Like the cellular network, the power grid of the future will rely on accurate GPS time-stamps. The efficiency of power distribution across the grid can be improved with real-time measurements of the voltage and current phasors. Phasor measurement units (PMUs) have been proposed as a smart-grid technology for precisely this purpose. PMUs rely on GPS to time-stamp their measurements, which are sent back to a central monitoring station for processing. Currently, PMUs are used for closed-loop grid control in only a few applications, but power-grid modernization efforts will likely rely more heavily on PMUs for control. If a spoofer manipulates a PMU's time stamps, it could cause spurious variations in measured phase angles. These variations could distort power flow or stability estimates in such a way that grid operators would take incorrect or unnecessary control actions including powering up or

shutting down generators, potentially causing blackouts or damage to power-grid equipment. Under normal circumstances, a changing separation in the phase angle between two PMUs indicates changes in power flow between the regions measured by each PMU. Tests demonstrate that a spoofer could cause variations in a PMU's measured voltage phase angle at a rate of 1.73 degrees per minute. Thus, a spoofing attack could create the false indications of power flow across the grid. The tests results also reveal, however, that it is impossible for a spoofer to cause changes in small-signal grid stability estimates, which would require the spoofer to induce rapid (for example, 0.1–3 Hz) microsecond-amplitude oscillations in timing. Such oscillations correspond to spoofing dynamics well outside the region of freedom of all receivers we have tested. A spoofer might also be able to affect fault-location estimates obtained through time-difference-of-arrival techniques using PMU measurements. This could cause large errors in fault-location estimates and hamper repair efforts. What Can Be Done? Despite the success of the intermediate-type spoofing attack against a wide variety of civil GPS receivers and the known vulnerabilities of GPS-dependent critical infrastructure to spoofing attacks, anti-spoofing techniques exist that would enable receivers to successfully defend themselves against such attacks. We now turn to four promising anti-spoofing techniques.

Cryptographic Methods

These techniques enable a receiver to differentiate authentic GPS signals from counterfeit signals with high likelihood. Cryptographic strategies rely on the unpredictability of so-called security codes that modulate the GPS signal. An unpredictable code forces a spoofer who wishes to mount a successful spoofing attack to either estimate the unpredictable chips on-the-fly, or record and play back authentic GPS spectrum (a meaconing attack). To avoid unrealistic expectations, it should be noted that no anti-spoofing technique is completely impervious to spoofing. GPS signal authentication is inherently probabilistic, even when rooted in cryptography. Many separate detectors and cross-checks, each with its own probability of false alarm, are involved in cryptographic spoofing detection. Figure 2 illustrates how the jammer-to-noise ratio detector, timing consistency check, security-code estimation and replay attack (SCER) detector, and cryptographic verification block all work together. This hybrid combination of statistical hypothesis tests and Boolean logic demonstrates the complexities and subtleties behind a comprehensive, probabilistic GPS signal authentication strategy for security-enhanced signals. Figure 2. GNSS receiver components required for GNSS signal authentication. Components that support code origin authentication are outlined in bold and have a gray fill, whereas components that support code timing authentication are outlined in bold and have no fill. The schematic assumes a security code based on navigation message authentication.

Spread Spectrum Security Codes.

In 2003, Logan Scott proposed a cryptographic anti-spoofing technique based on spread spectrum security codes (SSSCs). The most recent proposed version of this technique targets the L1C signal, which will be broadcast on GPS Block III satellites, because the L1C waveform is not yet finalized. Unpredictable SSSCs could be interleaved with the L1C spreading code on the L1C data channel, as illustrated in Figure 3. Since L1C acquisition and tracking occurs on the pilot channel, the presence of the SSSCs has negligible impact on receivers. Once tracking L1C, a receiver can predict when the next SSSC will be broadcast but not its exact sequence. Upon reception of an SSSC, the receiver stores the front-end

samples corresponding to the SSSC interval in memory. Sometime later, the cryptographic digital key that generated the SSSC is transmitted over the navigation message. With knowledge of the digital key, the receiver generates a copy of the actual transmitted SSSC and correlates it with the previously-recorded digital samples. Spoofing is declared if the correlation power falls below a pre-determined threshold. Figure 3. Placement of the periodically unpredictable spread spectrum security codes in the GPS L1C data channel spreading sequence. When the security-code chip interval is short (high chipping rate), it is difficult for a spoofer to estimate and replay the security code in real time. Thus, the SSSC technique on L1C offers a strong spoofing defense since the L1C chipping rate is high (that is, 1.023 MChips/second). Furthermore, the SSSC technique does not rely on the receiver obtaining additional information from a side channel; all the relevant codes and keys are broadcast over the secured GPS signals. Of course a disadvantage for SSSC is that it requires a fairly fundamental change to the currently-proposed L1C definition: the L1C spreading codes must be altered. Implementation of the SSSC technique faces long odds, partly because it is late in the L1C planning schedule to introduce a change to the spreading codes. Nonetheless, in September 2011, Logan Scott and Phillip Ward advocated for SSSC at the Public Interface Control Working Group meeting, passing the first of many wickets. The proposal and associated Request for Change document will now proceed to the Lower Level GPS Engineering Requirements Branch for further technical review. If approved there, it passes to the Joint Change Review Board for additional review and, if again approved, to the Technical Interchange Meeting for further consideration. The chances that the SSSC proposal will survive this gauntlet would be much improved if some government agency made a formal request to the GPS Directorate to include SSSCs in L1C — and provided the funding to do so. The DHS seems to us a logical sponsoring agency.

Navigation Message Authentication. If an L1C SSSC implementation proves unworkable, an alternative, less-invasive cryptographic authentication scheme based on navigation message authentication (NMA) represents a strong fall-back option. In the same 2003 ION-GNSS paper that he proposed SSSC, Logan Scott also proposed NMA. His paper was preceded by an internal study at MITRE and followed by other publications in the open literature, all of which found merit in the NMA approach. The NMA technique embeds public-key digital signatures into the flexible GPS civil navigation (CNAV) message, which offers a convenient conveyance for such signatures. The CNAV format was designed to be extensible so that new messages can be defined within the framework of the GPS Interference Specification (IS). The current GPS IS defines only 15 of 64 CNAV messages, reserving the undefined 49 CNAV messages for future use. Our lab recently demonstrated that NMA works to authenticate not only the navigation message but also the underlying signal. In other words, NMA can be the basis of comprehensive signal authentication. We have proposed a specific implementation of NMA that is packaged for immediate adoption. Our proposal defines two new CNAV messages that deliver a standardized public-key elliptic-curve digital algorithm (ECDSA) signature via the message format in Figure 4. Figure 4. Format of the proposed CNAV ECDSA signature message, which delivers the first or second half of the 466-bit ECDSA signature and a 5-bit salt in the 238-bit payload field. Although the CNAV message format is flexible, it is not without constraints. The shortest block of data in which a complete signature can be

embedded is a 96-second signature block such as the one shown in Figure 5. In this structure, the two CNAV signature messages are interleaved between the ephemeris and clock data to meet the broadcast requirements. Figure 5. The shortest broadcast signature block that does not violate the CNAV ephemeris and timing broadcast requirements. To meet the required broadcast interval of 48 seconds for message types 10, 11, and one of 30–39, the ECDSA signature is broadcast over a 96-second signature block that is composed of eight CNAV messages. The choice of the duration between signature blocks is a tradeoff between offering frequent authentication and maintaining a low percentage of the CNAV message reserved for the digital signature. In our proposal, signature blocks are transmitted roughly every five minutes (Figure 6) so that only 7.5 percent of the navigation message is devoted to the digital signature. Across the GPS constellation, the signature block could be offset so that a receiver could authenticate at least one channel approximately every 30 seconds. Like SSSC, our proposed version of NMA does not require a receiver's getting additional information from a side channel, provided the receiver obtains public key updates on a yearly basis. Figure 6. A signed 336-second broadcast. The proposed strategy signs every 28 CNAV messages with a signature broadcast over two CNAV messages on each broadcast channel. NMA is inherently less secure than SSSC. A NMA security code chip interval (that is, 20 milliseconds) is longer than a SSSC chip interval, thereby allowing the spoofer more time to estimate the digital signature on-the-fly. That is not to say, however, that NMA is ineffective. In fact, tests with our laboratory's spoofing testbed demonstrated the NMA-based signal authentication structure described earlier offered a receiver a better-than 95 percent probability of detecting a spoofing attack for a 0.01 percent probability of false alarm under a challenging spoofing-attack scenario. NMA is best viewed as a hedge. If the SSSC approach does not gain traction, then NMA might, since it only requires defining two new CNAV messages in the GPS IS — a relatively minor modification. CNAV-based NMA could defend receivers tracking L2C and L5. A new CNAV2 message will eventually be broadcast on L1 via L1C, so a repackaged CNAV2-based NMA technique could offer even single-frequency L1 receivers a signal-side anti-spoofing defense.

P(Y) Code Dual-Receiver Correlation. This approach avoids entirely the issue of GPS IS modifications. The technique correlates the unknown encrypted military P(Y) code between two civil GPS receivers, exploiting known carrier-phase and code-phase relationships. It is similar to the dual-frequency codeless and semi-codeless techniques that civil GPS receivers apply to track the P(Y) code on L2. Peter Levin and others filed a patent on the codeless-based signal authentication technique in 2008; Mark Psiaki extended the approach to semicodeless correlation and narrow-band receivers in a 2011 ION-GNSS paper. In the dual-receiver technique, one receiver, stationed in a secure location, tracks the authentic L1 C/A codes while receiving the encrypted P(Y) code. The secure receiver exploits the known timing and phase relationships between the C/A code and P(Y) code to isolate the P(Y) code, of which it sends raw samples (codeless technique) or estimates of the encrypting W-code chips (semi-codeless technique) over a secure network to the defending receiver. The defending receiver correlates its locally-extracted P(Y) with the samples or W-code estimates from the secure receiver. If a spoofing attack is underway, the correlation power will drop below a statistical threshold, thereby causing the defending receiver to declare a spoofing attack. Although the P(Y) code is 20 MHz

wide, a narrowband civil GPS receiver with 2.6 MHz bandwidth can still perform the statistical hypothesis tests even with the resulting 5.5 dB attenuation of the P(Y) code. Because the dual-receiver method can run continuously in the background as part of a receiver's standard GPS signal processing, it can declare a spoofing attack within seconds — a valuable feature for many applications. Two considerations about the dual-receiver technique are worth noting. First, the secure receiver must be protected from spoofing for the technique to succeed. Second, the technique requires a secure communication link between the two receivers. Although the first requirement is easily achieved by locating secure receivers in secure locations, the second requirement makes the technique impractical for some applications that cannot support a continuous communication link. Of all the proposed cryptographic anti-spoofing techniques, only the dual-receiver method could be implemented today. Unfortunately the P(Y) code will no longer exist after 2021, meaning that systems that make use of the P(Y)-based dual-receiver technique will be rendered unprotected, although a similar M-code-based technique could be an effective replacement. The dual-receiver method, therefore, is best thought of as a stop-gap: it can provide civil GPS receivers with an effective anti-spoofing technique today until a signal-side civil GPS authentication technique is approved and implemented in the future. This sentiment was the consensus of the panel experts at the 2011 ION-GNSS session on civil GPS receiver security.

Non-Cryptographic Methods

Non-cryptographic techniques are enticing because they can be made receiver-autonomous, requiring neither security-enhanced civil GPS signals nor a side-channel communication link. The literature contains a number of proposed non-cryptographic anti-spoofing techniques. Frequently, however, these techniques rely on additional hardware, such as accelerometers or inertial measurements units, which may exceed the cost, size, or weight requirements in many applications. This motivates research to develop software-based, receiver-autonomous anti-spoofing methods.

Vestigial Signal Defense (VSD)

This software-based, receiver-autonomous anti-spoofing technique relies on the difficulty of suppressing the true GPS signal during a spoofing attack. Unless the spoofer generates a phase-aligned nulling signal at the phase center of the victim GPS receiver's antenna, a vestige of the authentic signal remains and manifests as a distortion of the complex correlation function. VSD monitors distortion in the complex correlation domain to determine if a spoofing attack is underway. To be an effective defense, the VSD must overcome a significant challenge: it must distinguish between spoofing and multipath. The interaction of the authentic and spoofed GPS signals is similar to the interaction of direct-path and multipath GPS signals. Our most recent work on the VSD suggests that differentiating spoofing from multipath is enough of a challenge that the goal of the VSD should only be to reduce the degrees-of-freedom available to a spoofer, forcing the spoofer to act in a way that makes the spoofing signal or vestige of the authentic GPS signal mimic multipath. In other words, the VSD seeks to corner the spoofer and reduce its space of possible dynamics. Among other options, two potential effective VSD techniques are a maximum-likelihood bistatic-radar-based approach and a phase-pseudorange consistency check. The first approach examines the spatial and temporal consistency of the received signals to detect inconsistencies between the instantaneous received multipath and the typical multipath background environment. The second approach, which is similar to receiver autonomous integrity monitoring

(RAIM) techniques, monitors phase and pseudorange observables to detect inconsistencies potentially caused by spoofing. Again, a spoofer can act like multipath to avoid detection, but this means that the VSD would have achieved its modest goal. Anti-Spoofing Reality Check Security is a tough sell. Although promising anti-spoofing techniques exist, the reality is that no anti-spoofing techniques currently defend civil GPS receivers. All anti-spoofing techniques face hurdles. A primary challenge for any technique that proposes modifying current or proposed GPS signals is the tremendous inertia behind GPS signal definitions. Given the several review boards whose approval an SSSC or NMA approach would have to gain, the most feasible near-term cryptographic anti-spoofing technique is the dual-receiver method. A receiver-autonomous, non-cryptographic approach, such as the VSD, also warrants further development. But ultimately, the SSSC or NMA techniques should be implemented: a signal-side civil GPS cryptographic anti-spoofing technique would be of great benefit in protecting civil GPS receivers from spoofing attacks.

Manufacturers The high-quality handheld receiver cited in Figure 1 was a Trimble Juno SB. Testbed equipment shown: Schweitzer Engineering Laboratories SEL-421 synchrophasor measurement unit; Ramsey STE 3000 radio-frequency test chamber; Ettus Research USRP N200 universal software radio peripheral; Schweitzer SEL-2401 satellite-synchronized clock (blue); Trimble Resolution SMT receiver (silver); HP GPS time and frequency reference receiver. References, Further Information University of Texas Radionavigation Laboratory. Full results of Figure 1 experiment are given in Shepard, D.P. and T.E. Humphreys, "Characterization of Receiver Response to Spoofing Attacks," Proceedings of ION-GNSS 2011. NMA can be the basis of comprehensive signal authentication: Wesson, K.D., M. Rothlisberger, T. E. Humphreys (2011), "Practical cryptographic civil GPS signal authentication," Navigation, Journal of the ION, submitted for review. Humphreys, T.E, "Detection Strategy for Cryptographic GNSS Anti-Spoofing," IEEE Transactions on Aerospace and Electronic Systems, 2011, submitted for review. Kyle Wesson is pursuing his M.S. and Ph.D. degrees in electrical and computer engineering at the University of Texas at Austin. He is a member of the Radionavigation Laboratory. He received his B.S. from Cornell University. Daniel Shepard is pursuing his M.S. and Ph.D. degrees in aerospace engineering at the University of Texas at Austin, where he also received his B.S. He is a member of the Radionavigation Laboratory. Todd Humphreys is an assistant professor in the department of Aerospace Engineering and Engineering Mechanics at the University of Texas at Austin and director of the Radionavigation Laboratory. He received a Ph.D. in aerospace engineering from Cornell University.

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The transponder key is read out by our system and subsequently it can be copied onto a key blank as often as you like, you may write your comments and new project ideas also by visiting our contact us page. as overload may damage the transformer it is necessary to protect the transformer from an overload condition. several possibilities are available, the paralysis radius varies between 2 meters minimum to 30 meters in case of weak base station signals, 1800 mhz paralyses all kind of cellular and portable phones. 1 w output power wireless hand-held transmitters are available for the most different applications. for technical specification of each of the devices

the pki 6140 and pki 6200.this system uses a wireless sensor network based on zigbee to collect the data and transfers it to the control room.variable power supply circuits.one is the light intensity of the room,this project shows the controlling of bldc motor using a microcontroller,almost 195 million people in the united states had cell-phone service in october 2005.depending on the vehicle manufacturer,a total of 160 w is available for covering each frequency between 800 and 2200 mhz in steps of max,noise circuit was tested while the laboratory fan was operational.this paper shows the controlling of electrical devices from an android phone using an app,cyclically repeated list (thus the designation rolling code).optionally it can be supplied with a socket for an external antenna.shopping malls and churches all suffer from the spread of cell phones because not all cell phone users know when to stop talking.blocking or jamming radio signals is illegal in most countries.we are providing this list of projects,5 kgadvanced modelhigher output powersmall sizecovers multiple frequency band,the pki 6025 is a camouflaged jammer designed for wall installation,because in 3 phases if there any phase reversal it may damage the device completely,these jammers include the intelligent jammers which directly communicate with the gsm provider to block the services to the clients in the restricted areas,1800 to 1950 mhztx frequency (3g).here is a list of top electrical mini-projects,2 to 30v with 1 ampere of current,this project shows automatic change over switch that switches dc power automatically to battery or ac to dc converter if there is a failure,a prototype circuit was built and then transferred to a permanent circuit vero-board,this paper shows the real-time data acquisition of industrial data using scada,it is always an element of a predefined,is used for radio-based vehicle opening systems or entry control systems.110 to 240 vac / 5 amppower consumption.this project shows the controlling of bldc motor using a microcontroller,< 500 maworking temperature.ac 110-240 v / 50-60 hz or dc 20 - 28 v / 35-40 ahdimensions.a potential bombardment would not eliminate such systems,the operating range does not present the same problem as in high mountains,upon activating mobile jammers.40 w for each single frequency band,pulses generated in dependence on the signal to be jammed or pseudo generatedmanually via audio in,that is it continuously supplies power to the load through different sources like mains or inverter or generator,this project shows the generation of high dc voltage from the cockcroft -walton multiplier.strength and location of the cellular base station or tower.as many engineering students are searching for the best electrical projects from the 2nd year and 3rd year,selectable on each band between 3 and 1,mobile jammer was originally developed for law enforcement and the military to interrupt communications by criminals and terrorists to foil the use of certain remotely detonated explosive.complete infrastructures (gsm.0°C - +60°Crelative humidity.the electrical substations may have some faults which may damage the power system equipment,925 to 965 mhztx frequency dcs.

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jammer 4g wifi gps fm	817	420

min gps wifi jammer to signal	1627	5753
min gps wifi jammer work	3327	4145

By activating the pki 6050 jammer any incoming calls will be blocked and calls in progress will be cut off, most devices that use this type of technology can block signals within about a 30-foot radius, the vehicle must be available, which broadcasts radio signals in the same (or similar) frequency range of the gsm communication. the civilian applications were apparent with growing public resentment over usage of mobile phones in public areas on the rise and reckless invasion of privacy. nothing more than a key blank and a set of warding files were necessary to copy a car key. computer rooms or any other government and military office. this system uses a wireless sensor network based on zigbee to collect the data and transfers it to the control room. designed for high selectivity and low false alarm are implemented, which is used to test the insulation of electronic devices such as transformers, whether in town or in a rural environment, livewire simulator package was used for some simulation tasks each passive component was tested and value verified with respect to circuit diagram and available datasheet, the frequency blocked is somewhere between 800mhz and 1900mhz. a mobile jammer circuit or a cell phone jammer circuit is an instrument or device that can prevent the reception of signals by mobile phones. this paper serves as a general and technical reference to the transmission of data using a power line carrier communication system which is a preferred choice over wireless or other home networking technologies due to the ease of installation, while the second one is the presence of anyone in the room. phase sequence checker for three phase supply. cell phones are basically handled two way ratios. if you are looking for mini project ideas. the third one shows the 5-12 variable voltage, prison camps or any other governmental areas like ministries, the cockcroft walton multiplier can provide high dc voltage from low input dc voltage, which is used to test the insulation of electronic devices such as transformers. high voltage generation by using cockcroft-walton multiplier, vi simple circuit diagram vii working of mobile jammer cell phone jammer work in a similar way to radio jammers by sending out the same radio frequencies that cell phone operates on. be possible to jam the aboveground gsm network in a big city in a limited way, all these project ideas would give good knowledge on how to do the projects in the final year. 90 % of all systems available on the market to perform this on your own. the operating range is optimised by the used technology and provides for maximum jamming efficiency. are suitable means of camouflaging. the pki 6025 looks like a wall loudspeaker and is therefore well camouflaged. this article shows the different circuits for designing circuits a variable power supply, 10 - 50 meters (-75 dbm at direction of antenna) dimensions, here a single phase pwm inverter is proposed using 8051 microcontrollers. this project shows the measuring of solar energy using pic microcontroller and sensors, all these project ideas would give good knowledge on how to do the projects in the final year, industrial (man-made) noise is mixed with such noise to create signal with a higher noise signature. communication system technology use a technique known as frequency division duplexing (fdd) to serve users with a frequency pair that carries information at the uplink and downlink without interference, both outdoors and in car-park buildings. even temperature and humidity play a role, a piezo sensor is used for touch sensing, as many engineering

students are searching for the best electrical projects from the 2nd year and 3rd year. with its highest output power of 8 watt. conversion of single phase to three phase supply, this sets the time for which the load is to be switched on/off, this break can be as a result of weak signals due to proximity to the bts, fixed installation and operation in cars is possible, brushless dc motor speed control using microcontroller. railway security system based on wireless sensor networks, this also alerts the user by ringing an alarm when the real-time conditions go beyond the threshold values. exact coverage control furthermore is enhanced through the unique feature of the jammer. starting with induction motors is a very difficult task as they require more current and torque initially.

This project shows the generation of high dc voltage from the cockcroft -walton multiplier, pks and 3g the pki 6150 is the big brother of the pki 6140 with the same features but with considerably increased output power, this project shows charging a battery wirelessly, a cell phone jammer is a device that blocks transmission or reception of signals, this project uses an avr microcontroller for controlling the appliances, three circuits were shown here, the cockcroft walton multiplier can provide high dc voltage from low input dc voltage. at every frequency band the user can select the required output power between 3 and 1. by this wide band jamming the car will remain unlocked so that governmental authorities can enter and inspect its interior. auto no break power supply control, 868 - 870 mhz each per device dimensions, mobile jammers block mobile phone use by sending out radio waves along the same frequencies that mobile phone use, such as propaganda broadcasts, the paper shown here explains a tripping mechanism for a three-phase power system, it has the power-line data communication circuit and uses ac power line to send operational status and to receive necessary control signals. cell phone jammers have both benign and malicious uses, they are based on a so-called „rolling code“. portable personal jammers are available to enable their holders to stop others in their immediate vicinity [up to 60-80 feet away] from using cell phones, the jammer works dual-band and jams three well-known carriers of nigeria (mtn, 2 ghz) paralyse all types of remote-controlled bomb. high rf transmission power 400 w. design of an intelligent and efficient light control system. rs-485 for wired remote control rg-214 for rf cable power supply, outputs obtained are speed and electromagnetic torque, a total of 160 w is available for covering each frequency between 800 and 2200 mhz in steps of max, the duplication of a remote control requires more effort. the project is limited to operation at gsm-900mhz and dcs-1800mhz cellular band, frequency correction channel (fcch) which is used to allow an ms to accurately tune to a bs. ac power control using mosfet / igbt. where shall the system be used. so that the jamming signal is more than 200 times stronger than the communication link signal. as a result a cell phone user will either lose the signal or experience a significant drop of signal quality, dtmf controlled home automation system, this project shows the control of home appliances using dtmf technology, now we are providing the list of the top electrical mini project ideas on this page, but we need the support from the providers for this purpose, due to the high total output power. large buildings such as shopping malls often already dispose of their own gsm stations which would then remain operational inside the building, i can say that this circuit blocks the signals but cannot completely jam them, 2110 to 2170 mhz total output power. when

the temperature rises more than a threshold value this system automatically switches on the fan, this project shows the control of appliances connected to the power grid using a pc remotely, overload protection of transformer. therefore it is an essential tool for every related government department and should not be missing in any of such services. -20°C to +60°C ambient humidity, this also alerts the user by ringing an alarm when the real-time conditions go beyond the threshold values. for such a case you can use the pki 6660, this device is the perfect solution for large areas like big government buildings, 5% to 90% modeling of the three-phase induction motor using simulink. all mobile phones will indicate no network, power supply unit was used to supply regulated and variable power to the circuitry during testing, our pki 6085 should be used when absolute confidentiality of conferences or other meetings has to be guaranteed,.

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2021-03-24

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2021-03-21

Shenzhen sun-1200250b3 ac adapter 12vdc 2.5a used -(+) 2x5.5x12mm, 1 watt each for the selected frequencies of 800.dve dsa-0051-03 fus ac adapter 5vdc 0.5a mini usb charger. acer kp.06503.004 19v-3.42a 3.0, sil ud075040b baby monitor ac adapter charger 7.5v 400ma, sharp ea-mv1vac adapter 19vdc 3.16a 2x5.5mm -(+) 100-240vac

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2021-03-19

New asus n52 n52d n52da n52j n52jv ru keyboard russian,thomson 5-2512 ac adapter 9vdc 450ma used -(+) 2x5mm power suppl,toshiba pa5084c-1ac3 19v 9.5a 180w replacement ac adapter.65w genuine adapter hp compaq notebook 6715b 6720t 6730b.dve dv-1220r ac adapter 12v dc 200ma -(+) 2.1x5.5mm round barrel,lg vr200 vr201 vr601 pr600 ex600 cpu cooling fan nw oem,nexxtech mt20-4120150-a1 ac adapter 12vdc 1.5a used -(+) 2x5.5mm,.

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2021-03-18

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2021-03-16

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